

NUMERICAL RECIPES

Webnote No. 9, Rev. 1

Complete VEGAS Code

Here is the full listing of vegas and its accompanying utility routine rebin.

```
void vegas(VecDoub_I &regn, Doub fxn(VecDoub_I &, const Doub), const Int init,      vegas.h
    const Int ncall, const Int itmx, const Int nprn, Doub &tgral, Doub &sd,
    Doub &chi2a) {
```

Performs Monte Carlo integration of a user-supplied *ndim*-dimensional function *fxn* over a rectangular volume specified by *regn*[0..2**ndim*-1], a vector consisting of *ndim* "lower left" coordinates of the region followed by *ndim* "upper right" coordinates. The integration consists of *itmx* iterations, each with approximately *ncall* calls to the function. After each iteration the grid is refined; more than 5 or 10 iterations are rarely useful. The input flag *init* signals whether this call is a new start or a subsequent call for additional iterations (see comments in the code). The input flag *nprn* (normally 0) controls the amount of diagnostic output. Returned answers are *tgral* (the best estimate of the integral), *sd* (its standard deviation), and *chi2a* (χ^2 per degree of freedom, an indicator of whether consistent results are being obtained). See text for further details.

```
    static const Int NDMX=50, MXDIM=10, RANSEED=5330;
    static const Doub ALPH=1.5, TINY=1.0e-30;
    static Int i,it,j,k,mds,nd,ndo,ng,npg;
    static Doub calls,dv2g,dxg,f,f2,f2b,fb,rc,ti;
    static Doub tsi,wgt,xjac,xn,xnd,xo,schi,si,swgt;
    static VecInt ia(MXDIM),kg(MXDIM);
    static VecDoub dt(MXDIM),dx(MXDIM),r(NDMX),x(MXDIM),xin(NDMX);
    static MatDoub d(NDMX,MXDIM),di(NDMX,MXDIM),xi(MXDIM,NDMX);
    Best make everything static, allowing restarts.
    static Ran ran_vegas(RANSEED);      Initialize a captive, static random number gen-
                                        erator.

    Int ndim=regn.size()/2;
    if (init <= 0) {                    Normal entry. Enter here on a cold start.
        mds=ndo=1;                      Change to mds=0 to disable stratified sampling,
        for (j=0;j<ndim;j++) xi[j][0]=1.0;      i.e., use importance sampling only.
    }
    if (init <= 1) si=swgt=schi=0.0;
    Enter here to inherit the grid from a previous call, but not its answers.
    if (init <= 2) {                    Enter here to inherit the previous grid and its
        nd=NDMX;                        answers.
        ng=1;
        if (mds != 0) {                  Set up for stratification.
            ng=Int(pow(ncall/2.0+0.25,1.0/ndim));
            mds=1;
            if ((2*ng-NDMX) >= 0) {
                mds = -1;
                npg=ng/NDMX+1;
                nd=ng/npg;
                ng=npg*nd;
            }
        }
    }
    for (k=1,i=0;i<ndim;i++) k *= ng;
    npg=MAX(Int(ncall/k),2);
    calls=Doub(npg)*Doub(k);
```

```

dxg=1.0/ng;
for (dv2g=1,i=0;i<ndim;i++) dv2g *= dxg;
dv2g=SQR(calls*dv2g)/npg/npg/(npg-1.0);
xnd=nd;
dxg *= xnd;
xjac=1.0/calls;
for (j=0;j<ndim;j++) {
    dx[j]=regn[j+ndim]-regn[j];
    xjac *= dx[j];
}
if (nd != ndo) {
    Do binning if necessary.
    for (i=0;i<MAX(nd,ndo);i++) r[i]=1.0;
    for (j=0;j<ndim;j++)
        rebin(ndo/xnd,nd,r,xin,xi,j);
    ndo=nd;
}
if (nprn >= 0) {
    cout << " Input parameters for vegas";
    cout << " ndim= " << setw(4) << ndim;
    cout << " ncall= " << setw(8) << calls << endl;
    cout << setw(34) << " it=" << setw(5) << it;
    cout << " itmx=" << setw(5) << itmx << endl;
    cout << setw(34) << " nprn=" << setw(5) << nprn;
    cout << " ALPH=" << setw(9) << ALPH << endl;
    cout << setw(34) << " mds=" << setw(5) << mds;
    cout << " nd=" << setw(5) << nd << endl;
    for (j=0;j<ndim;j++) {
        cout << setw(30) << " x1[" << setw(2) << j;
        cout << "]=" << setw(11) << regn[j] << " xu[";
        cout << setw(2) << j << "]=" << " ";
        cout << setw(11) << regn[j+ndim] << endl;
    }
}
}
for (it=0;it<itmx;it++) {
Main iteration loop. Can enter here (init ≥ 3) to do an additional itmx iterations with
all other parameters unchanged.
    ti=tsi=0.0;
    for (j=0;j<ndim;j++) {
        kg[j]=1;
        for (i=0;i<nd;i++) d[i][j]=di[i][j]=0.0;
    }
    for (;;) {
        fb=f2b=0.0;
        for (k=0;k<npg;k++) {
            wgt=xjac;
            for (j=0;j<ndim;j++) {
                xn=(kg[j]-ran_vegas.doub())*dxg+1.0;
                ia[j]=MAX(MIN(Int(xn),NDMX),1);
                if (ia[j] > 1) {
                    xo=xi[j][ia[j]-1]-xi[j][ia[j]-2];
                    rc=xi[j][ia[j]-2]+(xn-ia[j])*xo;
                } else {
                    xo=xi[j][ia[j]-1];
                    rc=(xn-ia[j])*xo;
                }
                x[j]=regn[j]+rc*dx[j];
                wgt *= xo*xnd;
            }
            f=wgt*fxn(x,wgt);
            f2=f*f;
            fb += f;
            f2b += f2;
            for (j=0;j<ndim;j++) {

```

```

        di[ia[j]-1][j] += f;
        if (mds >= 0) d[ia[j]-1][j] += f2;
    }
}
f2b=sqrt(f2b*npg);
f2b=(f2b-fb)*(f2b+fb);
if (f2b <= 0.0) f2b=TINY;
ti += fb;
tsi += f2b;
if (mds < 0) {
    Use stratified sampling.
    for (j=0;j<ndim;j++) d[ia[j]-1][j] += f2b;
}
for (k=ndim-1;k>=0;k--) {
    kg[k] %= ng;
    if (++kg[k] != 1) break;
}
if (k < 0) break;
}
tsi *= dv2g;
wgt=1.0/tsi;
si += wgt*ti;
schi += wgt*ti*ti;
swgt += wgt;
tgral=si/swgt;
chi2a=(schi-si*tgral)/(it+0.0001);
if (chi2a < 0.0) chi2a = 0.0;
sd=sqrt(1.0/swgt);
tsi=sqrt(tsi);
if (nprn >= 0) {
    cout << " iteration no. " << setw(3) << (it+1);
    cout << " : integral = " << setw(14) << ti;
    cout << " +/- " << setw(9) << tsi << endl;
    cout << " all iterations: " << " integral =";
    cout << setw(14) << tgral << "+-" << setw(9) << sd;
    cout << " chi**2/IT n =" << setw(9) << chi2a << endl;
    if (nprn != 0) {
        for (j=0;j<ndim;j++) {
            cout << " DATA FOR axis " << setw(2) << j << endl;
            cout << "      X      delta i      X      delta i";
            cout << "      X      deltai" << endl;
            for (i=nprn/2;i<nd-2;i += nprn+2) {
                cout << setw(8) << xi[j][i] << setw(12) << di[i][j];
                cout << setw(12) << xi[j][i+1] << setw(12) << di[i+1][j];
                cout << setw(12) << xi[j][i+2] << setw(12) << di[i+2][j];
                cout << endl;
            }
        }
    }
}
for (j=0;j<ndim;j++) {
    xo=d[0][j];
    xn=d[1][j];
    d[0][j]=(xo+xn)/2.0;
    dt[j]=d[0][j];
    for (i=2;i<nd;i++) {
        rc=xo+xn;
        xo=xn;
        xn=d[i][j];
        d[i-1][j] = (rc+xn)/3.0;
        dt[j] += d[i-1][j];
    }
    d[nd-1][j]=(xo+xn)/2.0;
    dt[j] += d[nd-1][j];
}

```

Compute final results for this iteration.

Refine the grid. Consult references to understand the subtlety of this procedure. The refinement is damped, to avoid rapid, destabilizing changes, and also compressed in range by the exponent ALPH.

```

    for (j=0;j<ndim;j++) {
        rc=0.0;
        for (i=0;i<nd;i++) {
            if (d[i][j] < TINY) d[i][j]=TINY;
            r[i]=pow((1.0-d[i][j]/dt[j])/
                (log(dt[j])-log(d[i][j])),ALPH);
            rc += r[i];
        }
        rebin(rc/xnd,nd,r,xin,xi,j);
    }
}

```

```

rebin.h void rebin(const Doub rc, const Int nd, VecDoub_I &r, VecDoub_O &xin,
    MatDoub_IO &xi, const Int j) {

```

Utility routine used by vegas, to rebin a vector of densities contained in row j of xi into new bins defined by a vector r.

```

    Int i,k=0;
    Doub dr=0.0,xn=0.0,xo=0.0;

    for (i=0;i<nd-1;i++) {
        while (rc > dr)
            dr += r[(++k)-1];
        if (k > 1) xo=xi[j][k-2];
        xn=xi[j][k-1];
        dr -= rc;
        xin[i]=xn-(xn-xo)*dr/r[k-1];
    }
    for (i=0;i<nd-1;i++) xi[j][i]=xin[i];
    xi[j][nd-1]=1.0;
}

```